AVL-300 Specifications

GSM Specifications	
Frequency	Quad-Band: 850/900/1800/1900MHz Compliant to GSM Phase 2/2+ -Class 4 (2W @ 850/900MHz) -Class 1 (1W @ 1800/1900MHz)
GPRS	GPRS multi-slot class 12 GPRS mobile station class B
RMS Phase Error	5 deg
Max Out RF Power	$33.0dBm \pm 2dBm$
Dynamic Input Range	-15 ~ -102 dBm
Receiving Sensitivity	Class II RBER2%(-102dBm)
Stability Of Frequency	Greater than 2.5 ppm
Max Frequency Error	± 0.1 ppm
	GPS Specifications
GPS Chipset	UBlox. All-In-One receiver. Sensitive Fast and Accurate
Sensitivity	Autonomous: -148 dBm Hot Start: -160 dBm Tracking: -162 dBm
Position Accuracy	Without Aid: 3.0 m 2D-RMS DGPS: 2.5 m
TTFF (Open Sky)	Cold start 30s average Warm start <30s Hot start <1.2s
Interfaces	
Digital Inputs	Three digital inputs. One positive trigger for ignition detection. Two negative trigger inputs for panic button or other use.
Configurable Inputs	One special input can be configured to negative trigger digital input or analog input (0-2.8V)
Analog Input	One analog input (0-2.8V)

Digital Output	Two digital outputs, open drain, 150mA drive current max	
Latched Digital Outputs	One digital output with internal latch circuit, open drain, 150mA drive current max	
Two-Way Audio	Speaker and Microphone on 16 PIN connector	
GSM Antenna	Built in	
GPS Antenna	Built in or external (Optional, SMA RF connector)	
Serial Port	On MINI-USB for firmware upgrading and configuration	
General Specifications		
Dimension	80mm * 49mm * 26mm	
Weight	89 g	
Backup Battery	Li-Polymer 250 mAh, 3.7V	
Standby Time	Without reporting: 22 to 28 Hours 5 minute reporting: 10 to 12 Hours 10 minute reporting: 12 to 15 Hours	
Operation Voltage	8 to 32V DC	
Operation Temperature	-30°C ~ +80°C(Without Battery) -40°C ~ +85°C for Storage(Without Battery)	
Power Management	Full power pathing; Internal battery is not used when external power is available	
Air Interface Protocol		
Transmit Protocol	TCP, UDP, SMS	
Scheduled Timing Report	Position reports at pre-set time and distance intervals	
Geo-Fence	Geo-Fence alarm and parking alarm	
Low Power Alarm	Alarm when internal battery is almost exhausted	
Power On Report	Report when the device is powered on	
Tow Alarm	With built in motion sensor	
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Special Alarm	Special alarm based on the digital/analog inputs
Remote Control	Control the digital outputs through air interface protocol